

Day 0 Online 16 May	Introduction to points clouds	
	09h00-10h30 B. Bookhagen	Environmental point clouds <ul style="list-style-type: none"> • Point cloud sources: lidar (terrestrial, airborne), SFM, stereo satellites • Resolution, precision • Vegetation, file formats, data repositories
	-----	<i>Pause</i>
	10h45-12h15 D. Lague P. Leroy	Software tools: CloudCompare – part 1 <ol style="list-style-type: none"> 1a. Presentation of CloudCompare 1b. CloudCompare: GUI, cloning, subsampling, segmentation, merging, saving 2. LAS and LAZ files 3a. Scalar fields part 1 3b. Scalar fields part 2
	-----	<i>Lunch</i>
	13h45-14h15 D. Lague P.Leroy	Software tool: CloudCompare – part 2 <ol style="list-style-type: none"> 5. DEM, gridding, meshes 6. Classification
	-----	<i>Pause</i>
	14h30-16h00 D. Lague	Classification <ul style="list-style-type: none"> • Ground classification basics: geometrical methods (airborne) • Learning approaches • Challenges
16h15-17h30 B. Bookhagen	Software tool: python <ul style="list-style-type: none"> • Basics on python usage to visualize and process point clouds • First steps in python and some applications (e.g. alignment with Open3D) • Installation with pip, Miniconda / Anaconda 	

Workshop materials available

- On GitHub
 - <https://github.com/UP-RS-ESP/PointCloudWorkshop-May2022>
- On the summer school website
 - <https://clouds2022.sciencesconf.org/resource/page/id/3>
- On YouTube
 - <https://www.youtube.com/channel/UCgH2KZ0UdHYI7q2ddvpbjpQ>

Day 1 20 June	Change detection on point clouds: distance measurements with M3C2			
	08h30-09h00	Welcome, coffee		
	09h00-09h30 P. Leroy D. Lague B. Bookhagen	General introduction, tour de table		
	09h30-10h30 D. Lague	Theory: feature matching vs distance measurement, point to point, DoD, M3C2 (+ choice of parameters and their influence)		
	-----	<i>Pause</i>		
	10h45-12h15 D. Lague	Practical on CloudCompare: C2C, DoD, M3C2 (with a focus on parameter choices)		
	-----	<i>Lunch</i>		
	13h30-15h30 D. Lague	Theory / practical: dealing with uncertainties and limits of M3C2 Source of uncertainties depending on data sources		
	-----	<i>Pause</i>		
	15h45-16h45 P. Leroy	Short presentations of ½ of the participants and their datasets (5 minutes each).		
		Roberto Giudici	Jean-Baptiste Julien	Tassadit Kaci
		Sara Stuecker	Natacha Volto	Mohand Medjkane
Anne Duperret		Philipp Marr	Lea Matscheroth	
Guillaume Goodwin		Jan-Christophe Otto	Josh Ahmed	
Nathalie Barbosa	Marion Massé	Lovleen Acharya Chowdhury		
16h45-18h15 D. Lague P. Leroy	Practical on CloudCompare Various data sets and their specific aspects: ALS, TLS, SFM			

Day 2 21 June	Registration, alignment and inspection		
	08h30-09h15 B. Bookhagen	Theory: ICP (simple, global, etc.)	
	09h15-10h30 P. Leroy	Practical with CloudCompare <ul style="list-style-type: none"> • ICP • Quality control using M3C2 	
	-----	<i>Pause</i>	
	10h45-12h00 B. Bookhagen	Practical with python <ul style="list-style-type: none"> • Alignment with Open3D (point to plane) using the same dataset • Quality control 	
	-----	<i>Lunch</i>	
	13h00-13h30 D. Lague	Theory on segmentation, techniques Volume computation	
ROOM 1 - TD3 (first floor)			
Segmentation, CloudCompare, a bit of python			
13h30-15h30 T. Bernard	Presentation of a workflow to segment landslides and estimate the volume of sediments. Reference: Beyond 2D landslide inventories and their rollover: synoptic 3D inventories and volume from repeat lidar data Hands-on		
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15h45-17h00 T. Bernard D. Lague P. Leroy	Hands-on data processing, two options: <ul style="list-style-type: none"> • Data processing on personal data • Applying the previous workflow 		
ROOM 2 - Learning Lab (ground floor)			
Hands-on point clouds with python			
13h30-14h00 A. Rheinwalt	Pebble Segmentation using Point Clouds		
14h-00-17h00 A. Rheinwalt B. Bookhagen	Hands-on exercises and discussions (numpy, opencv, open3d): <ul style="list-style-type: none"> • Global alignment • Neighborhood-Feature based alignment • RGB-based alignment • SIFT-feature based alignment 		
17h15-18h15 P. Leroy	Short presentations of ½ the participants (5 minutes each).		
	Manudeo Singh	Solène ANTOINE	Daniel Lusk
	Léa Courtial-Manent	Celia Aranda Reina	Anya Towers
	Kristina Matraku	Guillaume Bouger	Mathilde Letard
	Martin Lund	Marko Kohv	Alex Andréault
	Anne-Laure Argentin	François Xavier Lamure	David Mair

Day 3 22 June Online Onsite	Invited speakers	
	08h30-09h15	Katharina Anders <i>3DGeo Research Group, Institute of Geography, Heidelberg University</i> It's about time... to observe surface dynamics in 4D point clouds
	09h15-10h00	Daniel Girardeau-Montaut <i>CloudCompare project</i> Presentation of the CloudCompare project and its latest developments
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	10h15-11h00	Chelsea Scott <i>Arizona State University</i> Measuring Change at the Earth's Surface with Topographic Differencing
	11h00-11h45	Antonio Abellan <i>Research Center on Alpine Environment, Valais, Switzerland</i> Cliff erosion / landslides
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	13h15-14h00	Fanny Brun <i>Univ. Grenoble Alpes, CNRS, IRD, Grenoble INP, IGE, Grenoble, France</i> Glacier mass change observations with remote sensing
	14h00-14h30	Iris De Gelis <i>Magellium, F-31000, Toulouse, France</i> <i>IRISA UMR 6074, Université Bretagne Sud, F-56000 Vannes, France</i> <i>CNES</i> Deep learning based 3D point clouds change detection: an application to cliffs dynamics
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	14h45-15h30	Zan Gojcic <i>Nvidia</i> Estimating dense 3D displacement vector fields for point cloud-based landslide monitoring
	15h30-16h00	Beth Pratt-Sitaula <i>UNAVCO</i> Point clouds in teaching: resources and strategies